

A New Conjugate Gradient Method for Unconstrained Optimization*

无约束优化中新的共轭梯度方法

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Abstract A new nonlinear conjugate gradient formula for solving unconstrained optimization problem is proposed. The formula satisfies the sufficient descent condition, and the method in which the proposed formula and the weak Wolfe conditions are used is global convergence. Preliminary numerical results show that the method is promising.

Key words unconstrained optimization, conjugate gradient, Wolfe line search, sufficient descent property, global convergence

摘要: 提出一个新的解决无约束最优化问题的非线性共轭梯度公式, 该公式满足充分下降条件, 采用这个公式和弱 Wolfe 条件的方法是全局收敛的. 初始的数值结果表明, 该方法是有前景的.

关键词: 无约束优化 共轭梯度 Wolfe 线搜索 充分下降性 全局收敛性

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1 Introduction

The nonlinear conjugate gradient (CG) method is quite suitable for solving large-scale unconstrained optimization problem

$$\min\{f(x) \mid x \in R^n\}, \quad (1.1)$$

where $f: \mathcal{R}^n \rightarrow \mathcal{R}$ is a twice continuously differentiable function whose gradient is denoted by $g: \mathcal{R}^n \rightarrow \mathcal{R}^n$, due to its simplicity and low memory requirement. Its iterative formula is given by

$$x_{k+1} = x_k + t_k d_k, \quad (1.2)$$

where t_k is a step size which is computed by carrying out a line search, and d_k is the search direction defined by

$$d_k = \begin{cases} -g^k, & \text{if } k = 1, \\ -g^k + U_k d_{k-1}, & \text{if } k \geq 2, \end{cases} \quad (1.3)$$

where U_k is a scalar and g^k denotes $g(x_k)$. There are at least six well-known formulae for U_k , which are given below:

$$U_k^{\text{HS}} = \frac{g_k^T (g_k - g_{k-1})}{(g_k - g_{k-1})^T d_{k-1}}, \quad (1.4)$$

$$U_k^{\text{FR}} = \frac{g_k^T g_k}{g_{k-1}^T g_{k-1}}, \quad (1.5)$$

$$U_k^{\text{PRP}} = \frac{g_k^T (g_k - g_{k-1})}{g_{k-1}^T g_{k-1}}, \quad (1.6)$$

$$U_k^{\text{ED}} = -\frac{g_k^T g_k}{d_{k-1}^T g_{k-1}}, \quad (1.7)$$

$$U_k^{\text{LS}} = -\frac{g_k^T (g_k - g_{k-1})}{d_{k-1}^T g_{k-1}}, \quad (1.8)$$

$$U_k^{\text{DY}} = \frac{g_k^T g_k}{(g_k - g_{k-1})^T d_{k-1}}. \quad (1.9)$$

To establish the global convergence results of the above CG methods, the step size t_k is usually required to satisfy some line search conditions, such as the weak Wolfe line search

$$f(x_k + t_k d_k) - f(x_k) \leq W_k g_k^T d_k, \quad (1.10)$$

$$g(x_k + t_k d_k)^T d_k \geq e_k^T d_k, \quad (1.11)$$

where $W \in (0, \frac{1}{2})$ and $e \in (W, 1)$, and the strong

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Wolfe line search (1. 10) and

$$|g(x^k + tk)^\top dk| \leq -\epsilon \|g^k\|^2, \quad (1. 12)$$

where $\epsilon \in (0, \frac{1}{2})$ and $\epsilon \in (W, 1)$.

Considerable attentions have been made on the global convergence behaviors for the above methods. Zoutendijk^[1] proved that the FR method with exact line search is globally convergent. Al-Baali^[2] extended this result to the strong Wolfe line search conditions. In Reference [3], Dai and Yuan proposed the DY method which produces a descent search direction at every iteration and converges globally provided that the line search satisfies the weak Wolfe conditions. However, the global convergence has not been established for the PRP method with the strong Wolfe line search conditions.

Under the sufficient descent condition

$$g^k \top dk \leq -c \|g^k\|^2, \quad (1. 13)$$

for some constant $c > 0$, Gilbert and Nocedal^[4] was in another way to discuss the global convergence of the PRP method with the weak Wolfe line search. In Reference [4], the parameter U_k in (1. 6) is not allowed to be negative, that is

$$U_k^{\dagger} = \max\{0, U_k^{\text{PRP}}\}. \quad (1. 14)$$

By using a complicated line search, Gilbert and Nocedal^[4] was able to establish the global convergence result of the PRP and the HS methods by restricting the scalar U_k to be nonnegative.

In this paper, we present our new CG formula and its properties in section 2, the global convergence result of this new method in section 3, preliminary numerical results in section 4, and conclusion in the last section.

2 New conjugate gradient formula and its property

The sufficient descent condition (1. 13) is an important property in the literature of analyzing the global convergence of the CG methods, so we intend to find a U_k such that dk satisfies the condition (1. 13). In the following, we propose a U_k and prove that it has such property.

A definition of a descent sequence (or a sufficient descent sequence) is given below. A sequence $\{U_k\}$ is called a descent sequence (or a sufficient descent sequence) for the CG methods if there exists a

constant $f \in (0, 1)$ (or $f \in [0, 1)$) such that for all $k \geq 2$,

$$U_k g^k \top dk_{k-1} \leq f \|g^k\|^2. \quad (2. 1)$$

In Reference [5], the authors proposed a variation of the FR formula (VFR):

$$U_k^{\text{VFR}} = \frac{{}_1 \|g^k\|^2}{{}_2 |g^k \top dk_{k-1}| + {}_3 \|g_{k-1}\|^2}, \quad (2. 2)$$

where ${}_1 \in (0, \infty)$, ${}_2 \in [1 + X, + \infty)$, ${}_3 \in (0, + \infty)$ and X is an any given positive constant. In Reference [6], the authors designed the following variation of the PRP formula

$$U_k^{\text{VPRP}} = \frac{{}_1 (\|g^k\|^2 - |g^k \top g_{k-1}|)}{{}_2 |g^k \top dk_{k-1}| + {}_3 \|g_{k-1}\|^2}, \quad (2. 3)$$

where the definitions of ${}_1, {}_2, {}_3$ are as same as those given in the formula (2. 2). In order to ensure the nonnegative of the parameter U_k , it is defined that

$$U_k^{\text{PRP}} = \max\{0, U_k^{\text{VPRP}}\}. \quad (2. 4)$$

It is easy to prove that $\{U_k^{\text{VFR}}\}$ and $\{U_k^{\text{VPRP}}\}$ all are descent sequence (with $f = \frac{1}{2}$). Further the formulae (2. 2) and (2. 4) make dk possess the sufficient descent property.

Enlightened by the above ideas, we propose a new U_k as follows

$$U_k^{\text{NPRP}} = \frac{\lambda {}_1 \|g^k\|^2 + (1 - \lambda) {}_1 (\|g^k\|^2 - |g^k \top g_{k-1}|)}{{}_2 |g^k \top dk_{k-1}| + {}_1 \|g_{k-1}\|^2}, \quad (2. 5)$$

where $\lambda \in (0, 1)$ and the definitions of ${}_1, {}_2$ are as same as those in the formula (2. 2). In order to ensure the nonnegative of the parameter U_k , we define

$$U_k^{\text{NPRP}} = \max\{0, U_k^{\text{NPRP}}\}, \quad (2. 6)$$

thus if a negative of U_k^{NPRP} occurs, this strategy will restart the iteration along the steepest direction.

The following two propositions show that the $\{U_k^{\text{NPRP}}\}$ is a descent sequence, and so that dk satisfies the sufficient descent condition (1. 13).

Proposition 2. 1 Suppose that U_k is defined by the formulae (2. 5) and (2. 6), then we have that

$$U_k^{\text{NPRP}} \leq \hat{\epsilon} \frac{\|g^k\|^2}{|g^k \top dk_{k-1}|}, \quad (2. 7)$$

where $0 < \hat{\epsilon} = \frac{1}{2} < 1$.

Proof It is clear that the inequality (2. 7) holds when $U_k^{\text{NPRP}} = 0$.

Now we consider the case where $U_k^{\text{NPRP}} = U_k^{\text{NPRP}}$.

So we have

$$U_k^{\text{NPRP}} =$$

$$\frac{\lambda_{-1} \|g_k\|^2 + (1-\lambda_{-1})(\|g_k\|^2 - |g_k^T g_{k-1}|)}{-2 |g_k^T d_{k-1}| + \lambda_{-1} \|g_{k-1}\|^2} \leq$$

$$\frac{\lambda_{-1} \|g_k^2\| + (1-\lambda_{-1}) \|g_k\|^2}{-2 |g_k^T d_{k-1}|} \leq$$

$$\frac{-1}{-2} \frac{\|g_k\|^2}{|g_k^T d_{k-1}|} = \hat{c} \frac{\|g_k\|^2}{|g_k^T d_{k-1}|}.$$

Hence U_k^{NPRP} can make the inequality (2.7) hold. Furthermore $\{U_k^{NPRP}\}$ is a descent sequence without any line search.

Proposition 2.2 Suppose that U_k is defined by the formulae (2.5) and (2.6), then d_k satisfies the sufficient descent condition(1.13) for all $k \geq 1$, where

$$c = (1 - \frac{1}{-2}).$$

Proof For any $k > 1$, suppose that $g_{k-1}^T d_{k-1} < 0$.

If $U_k^{NPRP} = 0$, then $d_k = -g_k$. So we have $g_k^T d_k = -\|g_k\|^2 \leq -c \|g_k\|^2$,

where $c = (1 - \frac{1}{-2})$.

Otherwise, from the definition of U_k^{NPRP} and Proposition 2.1, we can obtain

$$g_k^T d_k = g_k^T [-g_k + \frac{\lambda_{-1} \|g_k\|^2 + (1-\lambda_{-1})(\|g_k\|^2 - |g_k^T g_{k-1}|)}{-2 |g_k^T d_{k-1}| + \lambda_{-1} \|g_{k-1}\|^2} g_k^T g_{k-1}].$$

$$d_{k-1} \leq -\|g_k\|^2 + \frac{\lambda_{-1} \|g_k\|^2 + (1-\lambda_{-1})(\|g_k\|^2 - |g_k^T g_{k-1}|)}{-2 |g_k^T d_{k-1}| + \lambda_{-1} \|g_{k-1}\|^2} |g_k^T g_{k-1}|.$$

$$|g_k^T d_{k-1}| \leq -\|g_k\|^2 + \frac{1}{-2} \frac{\|g_k\|^2}{|g_k^T d_{k-1}|} |g_k^T d_{k-1}| \leq - (1 - \frac{1}{-2}) \|g_k\|^2 = -c \|g_k\|^2.$$

For $g_k^T d_1 = -\|g_1\|^2$, we can deduce that d_k has the sufficient descent condition (1.13) for all $k \geq 1$.

3 Algorithm and global convergence

Assumption A The level set $\Omega = \{x \in R^n | f(x) \leq f(x_1)\}$

is bounded.

Assumption B The gradient $g(x)$ is Lipschitz continuous, i. e, there exists a constant $L > 0$ such that for any $x, y \in \Omega$,

$$\|g(x) - g(y)\| \leq L \|x - y\|.$$

Now we give the algorithm:

Algorithm 3.1

Step 0 Given $x_1 \in R^n$, set $d_1 = -g_1, k = 1$. If $g_1 = 0$, then stop.

Step 1: Find a $t_k > 0$ satisfying the weak Wolfe

conditions (1.10) and (1.11).

Step 2 Let $x_{k+1} = x_k + t_k d_k$ and $g_{k+1} = g(x_{k+1})$. If $\|g_{k+1}\| = 0$, then stop.

Step 3 Compute U_{k+1}^{NPRP} by the formulae (2.5) and (2.6). Then generate d_{k+1} by the condition(1.3).

Step 4 Set $k = k + 1$, go to step 1.

Since $\{f(x_k)\}$ is a decreasing sequence, it is clear that the sequence $\{x_k\}$ is contained in Ω , and there exists a constant f^* , such that

$$\lim_{k \rightarrow \infty} f(x_k) = f^*. \tag{3.1}$$

By using the Assumptions A and B, we can deduce that there exists $M > 0$ such that

$$\|g_k\| \leq M, \forall x \in \Omega. \tag{3.2}$$

The following important result was obtained by Zoutendijk^[1] and Wolfe^[7,8].

Lemma 3.1 Suppose that $f(x)$ is bounded below, and $g(x)$ satisfies the Lipschitz condition. Consider any iteration method of the form (1.2), where d_k satisfies $d_k^T g_k < 0$ and t_k is obtained by the weak Wolfe line search. Then

$$\sum_{k=1}^{\infty} \frac{(g_k^T d_k)^2}{\|d_k\|^2} < +\infty. \tag{3.3}$$

The following lemma was obtained by Dai and Yuan^[9].

Lemma 3.2 Assumption that a positive series $\{a_i\}$ satisfies the following inequality for all k

$$\sum_{i=1}^k a_i \geq lk + c, \tag{3.4}$$

where $l > 0$ and c are constants. Then we have

$$\sum_{i=1}^{\infty} \frac{a_i^2}{i} = +\infty, \tag{3.5}$$

$$\text{and } \sum_{k=1}^{\infty} \frac{a_k^2}{\sum_{i=1}^k a_i} = +\infty. \tag{3.6}$$

Theorem 3.1 Suppose that Assumptions A and B hold, $\{x_k\}$ is a sequence generated by Algorithm 3.1, then we have

$$\lim_{k \rightarrow \infty} \inf \|g_k\| = 0 \tag{3.7}$$

holds.

Proof The condition(1.3) indicates that for all $k \geq 2$,

$$d_{k+1} + g_k = U_k d_{k-1}. \tag{3.8}$$

Squaring both sides of Formula(3.8), we obtain $\|d_k\|^2 = -\|g_k\|^2 - 2g_k^T d_k + U_k^2 \|d_{k-1}\|^2$.

$$\text{Suppose that } U_k^{NPRP} = U_k^{NPRP} \text{ in Formula(2.6).}$$

Then we have

$$\|d_k\|^2 = - \|g_k\|^2 - 2g_k^T d_k +$$

$$\left(\frac{\lambda_{-1} \|g_k\|^2 + (1-\lambda_{-1}) (\|g_k\|^2 - |g_k^T d_{k-1}|)}{\lambda_{-2} |g_k^T d_{k-1}| + \lambda_{-1} \|g_{k-1}\|^2} \right)^2.$$

$$\|d_{k-1}\|^2 \leq - \|g_k\|^2 - 2g_k^T d_k + \|g_k\|^4 \frac{\|d_{k-1}\|^2}{\|g_{k-1}\|^4},$$

that is

$$h_k \leq h_{k-1} - \frac{1}{\|g_k\|^2} + \frac{2V_k}{\|g_k\|^2}, \quad (3.10)$$

where $h_k = \frac{\|d_k\|^2}{\|g_k\|^4}$ and $V_k = - \frac{g_k^T d_k}{\|g_k\|^2}$.

Note that $h_1 = \frac{1}{\|g_1\|^2}$ and $V_1 = 1$, it follows Form (3.10) that

$$h_k \leq - \sum_{i=1}^k \frac{1}{\|g_i\|^2} + \sum_{i=1}^k \frac{|V_i|}{\|g_i\|^2}. \quad (3.11)$$

Suppose that the conclusion (3.7) is not held.

Then, there exists a positive scalar X such that for all $k \geq 1$,

$$\|g_k\| \geq X \quad (3.12)$$

Thus, it follows Forms (3.2) and (3.12) that

$$h_k \leq - \frac{k}{M^2} + \frac{2 \sum_{i=1}^k |V_i|}{X}. \quad (3.13)$$

Further, we have

$$h_k \leq \frac{2 \sum_{i=1}^k |V_i|}{X}. \quad (3.14)$$

On the other hand, using $h_k \geq 0$, the relation (3.13) implies that

$$\sum_{i=1}^k |V_i| \geq \frac{Xk}{2M^2}. \quad (3.15)$$

Using Lemmas 3.2 and (3.14), it follows that

$$\sum_{k=1}^{\infty} \frac{(g_k^T d_k)^2}{\|d_k\|^2} = \sum_{k=1}^{\infty} \frac{V_k^2}{h_k} = +\infty, \quad (3.16)$$

which contradicts to the Zoutendijk condition (3.3).

This shows that (3.7) holds, and the proof of this theorem is complete.

From the proof of the above theorem, we can conclude that any conjugate gradient method with the formula U_k^{NPRP} and some step size techniques which ensure the Zoutendijk condition (3.3) holds is globally convergent. In particular, the formula U_k^{NPRP} with the strong Wolfe conditions can generate a globally convergent method.

4 Numerical results

PRPSWP the PRP formula with the strong Wolfe conditions, where $W = 0.01$, $e = 0.1$.

PRP SWP the PRP formula with the strong

Wolfe conditions, where $W = 0.01$, $e = 0.1$.

NPRP SWP the new CG formula U_k^{NPRP} given in this paper with the strong Wolfe conditions, where $W = 0.01$, $e = 0.1$, $\lambda = 0.3$, $\lambda_{-1} = 1$, $\lambda_{-2} = 3$.

NPRP WWP the new CG formula U_k^{NPRP} given in this paper with the weak Wolfe conditions, where $W = 0.01$, $e = 0.1$, $\lambda = 0.3$, $\lambda_{-1} = 1$, $\lambda_{-2} = 3$.

Further, the results of the performed comparison with the original PRP method are given. The problems that we tested are from Reference [10]. For each tested problem, the termination condition is

$$\|g(x_k)\| \leq 10^{-5}.$$

Table 1 shows the computation results, where the columns have the following meanings

Problem the name of the test problem in

MATLAB;

Dim the dimension of the problem;

NI the number of iterations;

NE the number of function evaluations;

NG the number of gradient evaluations.

In order to rank the iterative numerical methods, we compute the total numbers of function and gradient evaluations by the following formula

$$N_{total} = NF + m^* NG, \quad (4.1)$$

where m is an integer. According to the results on automatic differentiation^[10,11], the value of m can be set to $m = 5$.

Since the PRPSWP method is one of the commonly efficient CG methods, we compare the PRP SWP, the NVPRP SWP and the NVPRP WWP methods with the PRPSWP method as follows for each tested example i , compute the total numbers of function evaluations and gradient evaluations required by the evaluated method j ($EM(j)$) and the PRPSWP method by the formula (4.1), and denote them by $N_{total,i}(EM(j))$ and $N_{total,i}(PRPSWP)$; then calculate the ratio

$$r_i(EM(j)) = \frac{N_{total,i}(EM(j))}{N_{total,i}(PRPSWP)}. \quad (4.2)$$

If $EM(j_0)$ does not work for example i_0 , we replace the $r_{i_0}(EM(j_0))$ by a positive constant f which is defined as follows

$$f = \max\{r_i(EM(j)); (i,j) \notin S_i\},$$

Table 1 Test results for the PRPSWP, PRP SWP, NPRP SWP, NPRP WWP

Problem	Dim	PRPSWP	PRP SWP	NPRP SWP	NPRP WWP
		NI/NF/NG	NI/NF/NG	NI/NF/NG	NI/NF/NG
ROSE	2	29/502/65	22/394/60	28/318/67	28/355/59
FROTH	2	12/30/20	10/28/20	13/83/25	28/57/41
BADSCP	2	–	41/509/100	34/324/100	55/268/98
BADSCB	2	13/80/22	11/123/22	16/82/25	19/86/29
BEALE	2	9/126/21	9/173/20	20/96/36	19/44/31
JENSAM	2	–	–	11/172/18	13/30/18
HELIX	3	49/255/83	32/265/55	42/283/66	34/81/53
BARD	3	23/98/37	27/152/43	17/134/28	53/98/74
GAUSS	3	4/57/6	4/57/6	3/7/4	3/7/4
MEYER	3	–	–	–	3/7/4
GULF	3	1/2/2	1/2/2	1/2/2	1/2/2
BOX	3	–	–	–	–
SING	4	199/611/338	49/155/79	27/351/44	27/351/44
WOOD	4	169/1103/302	101/549/195	56/128/95	85/223/132
KOWOSB	4	55/300/94	51/249/79	16/282/25	16/282/25
BD	4	–	–	–	–
OSB ₁	5	–	–	–	–
BIGGS	6	264/875/423	–	43/486/244	43/486/244
OSB ₂	11	254/1061/418	250/1011/412	–	476/1279/644
WATSON	20	2795/7733/4425	2143/5780/3396	1523/3836/2394	1513/3351/2233
ROSEX	8	23/402/59	25/371/62	32/329/72	34/88/59
	50	31/533/77	24/492/60	32/324/62	38/186/68
	100	28/337/74	35/514/101	25/401/63	25/186/63
SINGX	4	199/611/338	49/155/79	56/128/95	56/128/95
PEN ₁	2	5/18/12	6/20/14	5/18/12	5/18/12
PEN ₂	4	12/134/28	12/136/27	10/81/25	11/75/18
	50	613/2795/1063	136/898/282	129/824/252	129/364/227
WARDIM	2	3/9/7	3/9/7	3/9/7	3/9/7
	50	10/52/36	10/52/36	10/52/36	10/52/36
TRIG	3	12/81/24	14/131/25	13/228/26	16/182/22
	50	41/279/72	41/230/72	39/372/71	41/167/52
	100	46/342/87	46/341/85	63/352/110	63/204/86
BV	3	12/25/16	12/25/16	8/17/11	8/17/11
	10	75/241/117	75/241/117	158/533/254	177/335/233
IE	3	5/12/7	5/12/7	5/12/7	5/12/7
	50	6/13/7	5/11/6	5/11/6	5/11/6
	100	6/13/8	6/13/8	6/13/8	6/13/8
	200	6/13/8	6/13/8	6/13/8	6/12/7
	500	6/13/8	6/13/8	6/13/8	6/13/8
TRID	3	10/75/16	13/33/19	13/77/17	18/35/19
	50	26/55/31	26/55/31	28/58/35	26/51/29
	100	30/67/36	30/67/36	31/68/38	29/63/34
	200	30/66/36	30/66/36	30/66/39	29/58/33
BAND	3	9/68/13	10/23/17	7/64/12	7/17/10
	50	18/183/24	16/331/25	16/184/23	17/182/22
	100	18/183/24	16/373/26	17/375/27	20/142/27
	200	19/283/27	17/340/27	17/147/25	17/327/22
LIN	2	1/3/3	1/3/3	1/3/3	1/3/3
	50	1/3/3	1/3/3	1/3/3	1/3/3
	500	1/3/3	1/3/3	1/3/3	1/3/3
	1000	1/3/3	1/3/3	1/3/3	1/3/3
LIN ₁	2	1/51/2	1/51/2	1/51/2	1/51/2
	10	1/3/3	1/3/3	1/3/3	1/3/3
LIN ₂	4	1/3/3	1/3/3	1/3/3	1/3/3

where $S_i = \{(i, j): \text{method } j \text{ does not work for example } i\}$. The geometric mean of these ratios for method $EM(j)$ over all the test problems is defined by

$$r(EM(j)) = \left(\prod_{\epsilon \in S} n(EM(j)) \right)^{1/|S|}, \quad (4.3)$$

where S denotes the set of the test problems and $|S|$ is the number of elements in S . One advantage of the above rule is that, the comparison is relative and hence does not to be dominated by a few problems for which the method requires a great deal of function evaluations and gradient functions.

According to the above rules, it is clear that $r(\text{PRPSWP}) = 1$. The values of $r(\text{PRP SWP})$, $r(\text{NPRP SWP})$ and $r(\text{NPRP WWP})$ are listed in Table 2. As we can see from Table 2, the new method is much better than the PRP method.

Table 2 Relative efficiency of PRPSWP, PRP SWP, NPRP SWP, NPRP WWP

PRPSWP	PRP SWP	NPRP SWP	NPRP WWP
1	0.9049	0.8526	0.7725

5 Conclusion

By the combination of the variation of the formulae U_k^{FR} and U_k^{PRP} , we have found the new formula possesses the following features: (1) $\{U_k^{NPRP}\}$ is a descent sequence without any line search; (2) the new method possesses the sufficient descent property and converge globally; (3) the strategy will restart the iteration automatically along the steepest descent direction if a negative value of U_k^{NPRP} occurs; (4) the initial numerical results are promising.

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抗精神病药物思瑞康有助戒毒

美国匹兹堡大学医学院的专家给予 213 例门诊戒毒病人服用 25mg 装的思瑞康, 每 4h 服用 1-2 粒, 以帮助抵抗毒瘾发作。如果病人对这一剂量的思瑞康产生了耐药性, 医生就会为其加量。41% 的病人最终完成了疗程, 他们能至少持续 5 天不吸毒。此后, 该医学院对 107 例戒毒病人进行问卷调查, 其中 79 例病人报告说思瑞康帮助他们缓解了毒瘾; 52 例病人称该药缓解了毒瘾发作时的焦虑症状; 24 例病人认为该药有助于减轻疼痛; 22 例病人感到失眠症状减少; 14 例病人觉得胃口大增。只有 4 例病人感觉没有效果, 另外 7 例病人因无法忍受药物的副作用放弃了治疗。

(据科学网)