Uniqueness of Solutions to a Degenerate Parabolic Equation

一种退化抛物方程广义解的惟一性

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Abstract: The uniqueness of solutions to the initial boundary value problems of a degenerate parabolic equation is proved by means of a regularizing technique based on elliptic operators.

Key words: parabolic equation, uniqueness, elliptic operator

摘要:借助正则化技术,基于椭圆算子证明一种退化抛物方程初边值问题广义解的惟一性.

关键词:抛物方程 惟一性 椭圆算子

中图法分类号:O175.29 文献标识码:A 文章编号:1005-9164(2006)03-0177-03

1 Introduction

This paper is concerned to the uniqueness of solutions to the following initial boundary value problems

$$\frac{\partial C(u)}{\partial t} = \Delta A(u) + \operatorname{div} \vec{B}(u), (x,t) \in Q_T,$$

(1.1)

$$A(u(x,t)) = 0, (x,t) \in \partial\Omega \times (0,T), \quad (1.2)$$

$$C(u(x,0)) = u_0(x), x \in \Omega. \tag{1.3}$$

Where Ω is a bounded domain with smooth boundary in R^N , $Q_T = \Omega \times (0,T)$, A(s) and C(s) are continuous differential function on R with $A'(s) \geq 0$ and $C'(s) \geq 0$, $A(s) = \Phi_1(C(s))$, $\vec{B}(s) = \vec{\Phi}_2(A(s))$ and $\Phi_1(s)$, $\vec{\Phi}_2(s)$ are locally Lipschite continuously functions and $u_0(x) \in L^\infty(\Omega)$.

Equation (1.1) is a kind of equation with double degeneracies. Generally, as $C'(s) \neq 0$, this is a typical parabolic-hyperbolic mixed equation, which degenerates when A'(s) = 0. Similarly, as $A'(s) \neq 0$, it is the elliptic-parabolic mixed type, which degenerates when C'(s) = 0. And its significance is not only due to theoretical research but also due to its

physical background. In the case of C(s)=s, this kind of equations have been paid much attention by many pioneers. The discussion of existence and uniqueness of solutions can be found in many papers^[1~5].

In this paper, we deal with the uniqueness of generalized solutions to the problems $(1,1) \sim (1,3)$. The method used was inspired by some ideas of Brézis and Crandall^[6]. We do not consider the Cauchy problem but the initial boundary value problem, so the regularizing procedure is achieved by means of an elliptic operator.

Definition 1. 1 A function u(x,t) is called a generalized solution of the initial boundary value problems $(1,1)\sim (1,3)$, if $u\in L^\infty(Q_T)$, $A(u)\in L^2(0,T;H^1_0(\Omega))$, $C(u)\in BV(Q_T)$, and for any test function $\varphi\in C^\infty(\bar{Q}_T)$ with $\varphi(x,t)=0$ for $x\in\partial\Omega$ and for t=T, then the following integral equality holds

$$\iint_{Q_T} (C(u) \frac{\partial \varphi}{\partial t} + A(u) \Delta \varphi - \vec{B}(u) \cdot \nabla \varphi) dx dt +$$

$$\int_{\Omega} u_0(x)\varphi(x,0)\mathrm{d}x = 0. \tag{1.4}$$

2 Results

Theorem 2.1 If u_1, u_2 are two generalized solutions of the initial boundary value problems (1.1) $\sim (1.3)$, then $C(u_1) = C(u_2)$ a. e. in Q_T .

收稿日期:2006-01-24

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广西科学 2006年8月 第13卷第3期

Proof Since $u_1,u_2\in L^\infty(Q_T)$ are two generalized solutions of the problems $(1,1)\sim(1,3)$, by the definition of generalized solutions, for any test function $\varphi\in C^\infty(\overline{Q}_T)$ with $\varphi(x,t)=0$ for $x\in\partial\Omega$ and for t=T, we have

$$\iint_{Q_T} \overline{C} \frac{\partial \varphi}{\partial t} dx dt + \iint_{Q_T} \overline{A} \Delta \varphi dx dt - \iint_{Q_T} \overrightarrow{H} \cdot \nabla \varphi dx dt = 0,$$
where

$$\overline{C} = C(u_1) - C(u_2), \overline{A} = A(u_1) - A(u_2), \overrightarrow{H} = \overrightarrow{B}(u_1) - \overrightarrow{B}(u_2).$$

We assert that $\overline{C} = 0$ a. e. in Q_T . From this equality one can choose special test functions φ .

For small $\lambda>0$, we define the operator T_λ as the following

$$T_{\lambda}: L^{2}(\Omega) \to L^{2}(\Omega), f| \to u$$
,

where $u = T_{\lambda}$ and f is determined uniquely by the Dirichlet problem

$$-\Delta u + \lambda u = f, x \in \Omega,$$

$$u = 0, x \in \partial\Omega.$$
(2.2)

It is easy to see that T_{λ} is a self-adjoint operator, i. e., for arbitrary $f,g\in L^2(\Omega)$,

$$\int_{\Omega} f T_{\lambda} g \mathrm{d}x = \int_{\Omega} g T_{\lambda} f \mathrm{d}x,$$

and from the L^2 theory for elliptic equations, we have

$$||T_{\lambda}f||_{L^2(\Omega)} \leqslant C_0 ||f||_{L^2(\Omega)},$$

where C_0 is a constant depending only on N and Ω but independent of λ and f.

Replace φ by $T_{\lambda}\varphi$ in the formula (2.1), we get

$$\iint_{Q_{T}} \overline{C} \, \frac{\partial T_{\lambda} \varphi}{\partial t} dx dt + \iint_{Q_{T}} \overline{A} \Delta T_{\lambda} \varphi dx dt - \iint_{Q_{T}} \vec{H} \cdot \nabla T_{\lambda} \varphi dx dt = \iint_{Q_{T}} \overline{C} T_{\lambda} (\frac{\partial \varphi}{\partial t}) dx dt + \iint_{Q_{T}} \overline{A} (\lambda T_{\lambda} \varphi - \varphi) dx dt + \iint_{Q_{T}} (\operatorname{div} \vec{H}) T_{\lambda} \varphi dx dt = \iint_{Q_{T}} \frac{\partial \varphi}{\partial t} T_{\lambda} \overline{C} dx dt + \iint_{Q_{T}} (\lambda T_{\lambda} \overline{A} - \overline{A}) \varphi \, dx dt + \iint_{Q_{T}} T_{\lambda} (\operatorname{div} \vec{H}) \varphi \, dx dt = \iint_{Q_{T}} -\frac{\partial T_{\lambda} \overline{C}}{\partial t} \varphi \, dx dt + \iint_{Q_{T}} (\lambda T_{\lambda} \overline{A} - \overline{A}) \varphi \, dx dt + \iint_{Q_{T}} T_{\lambda} (\operatorname{div} \vec{H}) \varphi \, dx dt + \iint_{Q_{T}} T_{\lambda} (\operatorname{div} \vec{H}) \varphi \, dx dt = 0.$$

Owing to the arbitrariness of φ , we have that

$$\frac{\partial T_{\lambda} \overline{C}}{\partial t} = \lambda T_{\lambda} \overline{A} - \overline{A} + T_{\lambda} (\operatorname{div} \vec{H})$$
 (2.3)

in the sense of distribution.

Denote

$$g_{\lambda}(t) = \int_{\Omega} \overline{C}(x,t) T_{\lambda} \overline{C}(x,t) dx,$$

we can prove that

$$\lim_{\lambda \to 0} g_{\lambda}(t) = 0, \quad a.e. t \in (0,T). \tag{2.4}$$

Once this is done, owing to the fact that

$$g_{\lambda}(t) = \int_{a} \overline{C}(x,t) T_{\lambda} \overline{C}(x,t) dx =$$

$$\int_{a} (\lambda T_{\lambda} \overline{C}(x,t) - \Delta T_{\lambda} \overline{C}(x,t)) T_{\lambda} \overline{C}(x,t) dx =$$

$$\lambda \| T_{\lambda} \overline{C}(.,t) \|_{2}^{2} + \| \nabla T_{\lambda} \overline{C}(.,t) \|_{2}^{2},$$

we have, for almost all $t \in (0,T)$,

$$\lim_{\lambda \to 0} \lambda T_{\lambda} \ \overline{C}(.,t) = 0, \ \lim_{\lambda \to 0} \nabla T_{\lambda} \ \overline{C}(.,t) = 0, \text{in}$$

$$L^{2}(\Omega).$$

It follows that, in particular in the sense of distributions,

$$\lim_{\lambda \to 0} \lambda T_{\lambda} \ \overline{C}(.,t) = 0, \lim_{\lambda \to 0} \Delta T_{\lambda} \ \overline{C}(.,t) = 0, \text{in}$$

$$L^{2}(\Omega),$$

and hence

$$\overline{C}(.,t) = \lim_{\lambda \to 0} (\lambda T_{\lambda} \overline{C}(.,t) - \Delta T_{\lambda} \overline{C}(.,t)) = 0, \text{in}$$

$$L^{2}(\Omega).$$

This shows that $\overline{C} = C(u_1) - C(u_2) = 0$ in a. e. Q_T .

Now we turn to the proof of the formula (2.4). Let J_{ϵ} be the standard mollifier in t. From the formula (2.3) and the symmetry of T_{λ} , we have

$$\frac{\mathrm{d}}{\mathrm{d}t} \int_{\Omega} T_{\lambda} (J_{\epsilon} \, \overline{C}) J_{\epsilon} \, \overline{C} \mathrm{d}x = 2 \int_{\Omega} \frac{\partial}{\partial t} T_{\lambda} (J_{\epsilon} \, \overline{C}) J_{\epsilon} \, \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\frac{\partial}{\partial t} T_{\lambda} \, \overline{C}) J_{\epsilon} \, \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A} + \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A} - \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_{\epsilon} (\lambda T_{\lambda} \, \overline{A}) \int_{\Omega} \overline{C} \mathrm{d}x = 2 \int_{\Omega} J_$$

 $T_{\lambda}(\operatorname{div}\vec{H}))J_{\varepsilon}\overline{C}\mathrm{d}x.$

Integrating with respect to t give

$$\int_{\Omega} T_{\lambda}(J_{\epsilon} \overline{C}(x,t)) J_{\epsilon} \overline{C}(x,t) dx =$$

$$\int_{\Omega} T_{\lambda}(J_{\epsilon} \overline{C}(x,0)) J_{\epsilon} \overline{C}(x,0) dx + 2 \iint_{Q_{\epsilon}} J_{\epsilon}(\lambda T_{\lambda} \overline{A} - \overline{A} + T_{\lambda}(\operatorname{div} \vec{H})) J_{\epsilon} \overline{C} dx ds.$$
Let $\epsilon \to 0$ and note $\overline{C}(x,0) = C(u_{1}(x,0)) - C(u_{2}(x,0)) = u_{0}(x) - u_{0}(x) = 0$, we have
$$g_{\lambda}(t) = 2 \iint_{Q_{\epsilon}} (\lambda T_{\lambda} \overline{A} - \overline{A} + T_{\lambda}(\operatorname{div} \vec{H})) \overline{C} dx ds.$$
(2.5)

From $C(u_1)$, $C(u_2) \in BV(Q_T)$, we know that \overline{C} is bounded, A(s), C(s) are continuously differentiable and $\Phi_1(s)$, $\overline{\Phi}_2(s)$ are locally Lipschite continuous, there must exist two positive constants M_0 and M_1 such that the following estimate holds

$$|\overline{A}| \leqslant M_0 |\overline{C}|, |\overline{H}| \leqslant M_1 |\overline{A}|.$$

 \overline{C} and \overline{A} have the same sign due to the assumption that $A'(s) \geqslant 0$ and $C'(s) \geqslant 0$, we get

$$\overline{C}\,\overline{A} = |\,\overline{C}\,|\,|\,\overline{A}\,| \geqslant \frac{1}{M_0}|\,\overline{A}\,|^2.$$

By using of Schwartz's inequality and Young's

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inequality, we get

$$\begin{split} |\int_{a}T_{\lambda}(\operatorname{div}\overrightarrow{H})\cdot\overline{C}\mathrm{d}x| &= |\int_{a}\operatorname{div}\overrightarrow{H}\cdot T_{\lambda}\overline{C}\mathrm{d}x| = \\ |\int_{a}\overrightarrow{H}\cdot\nabla T_{\lambda}\overline{C}\mathrm{d}x| &\leq (\int_{a}|\overrightarrow{H}|^{2}\mathrm{d}x)^{1/2}\cdot\\ (\int_{a}|\nabla T_{\lambda}\overline{C}|^{2}\mathrm{d}x)^{1/2} &\leq M_{1}(\int_{a}|\overline{A}|^{2}\cdot\\ \operatorname{d}x)^{1/2}(\int_{a}|\nabla T_{\lambda}|\overline{C}|^{2}\mathrm{d}x)^{1/2} &\leq \frac{1}{M_{0}}\int_{a}|\overline{A}|^{2}\mathrm{d}x +\\ \frac{M_{0}M_{1}^{2}}{4}\int_{a}|\nabla T_{\lambda}\overline{C}|^{2}\mathrm{d}x &= \frac{1}{M_{0}}\int_{a}|\overline{A}|^{2}\mathrm{d}x - \frac{M_{0}M_{1}^{2}}{4}\int_{a}T_{\lambda}\overline{C}(\lambda T_{\lambda}\overline{C} -\\ \overline{C}\Delta T_{\lambda}\overline{C}\mathrm{d}x &= \frac{1}{M_{0}}\int_{a}|\overline{A}|^{2}\mathrm{d}x - \frac{M_{0}M_{1}^{2}}{4}\int_{a}T_{\lambda}\overline{C}(\lambda T_{\lambda}\overline{C} -\\ \overline{C})\mathrm{d}x &= \frac{1}{M_{0}}\int_{a}|\overline{A}|^{2}\mathrm{d}x - \frac{M_{0}M_{1}^{2}}{4}\lambda\int_{a}|T_{\lambda}|\overline{C}|^{2}\mathrm{d}x +\\ \frac{M_{0}M_{1}^{2}}{4}\int_{a}T_{\lambda}\overline{C}\cdot\overline{C}\mathrm{d}x &\leq \frac{1}{M_{0}}\int_{a}|\overline{A}|^{2}\mathrm{d}x + \frac{M_{0}M_{1}^{2}}{4}g_{\lambda}(t). \end{split}$$

Therefore, from the formula (2.5), we have

$$g_{\lambda}(t) = 2 \iint_{Q_{t}} (\lambda T_{\lambda} \overline{A} - \overline{A} + T_{\lambda}(\operatorname{div} \vec{H})) \, \overline{C} dx ds \leqslant$$

$$2 M_{0} \lambda \iint_{Q_{t}} |\overline{C} T_{\lambda} \, \overline{C}| \, dx ds + \frac{M_{0} M_{1}^{2}}{2} \int_{0}^{t} g_{\lambda}(s) ds.$$

On the other hand, for the solution $u = T_{\lambda}f$ of the formula (2.2), it is easily seen that

$$\int_{\Omega} |\nabla T_{\lambda} f|^{2} dx + \lambda \int_{\Omega} |T_{\lambda} f|^{2} dx \leqslant C \int_{\Omega} |f|^{2} dx.$$

Using Sobolev's inequality we get

$$\int_{\Omega} |T_{\lambda}f|^2 \mathrm{d}x \leqslant C \int_{\Omega} |f|^2 \mathrm{d}x.$$

Hence

$$\begin{split} g_{\lambda}(t) &\leqslant 2M_0 \lambda \!\! \int_{Q_t} \!\! \mid \overline{C}T_{\lambda} \, \overline{C} \! \mid \! \mathrm{d}x \mathrm{d}s + \\ &\frac{M_0 M_1^2}{2} \!\! \int_0^t \!\! g_{\lambda}(s) \mathrm{d}s \leqslant M_0 \lambda \!\! \int_{Q_t} \!\! (\mid \overline{C}\mid^2 + \mid \!\! T_{\lambda} \, \overline{C}\mid^2) \mathrm{d}x \mathrm{d}s + \\ &\frac{M_0 M_1^2}{2} \!\! \int_0^t \!\! g_{\lambda}(s) \mathrm{d}s \leqslant C_1 \lambda \!\! \int_{Q_t} \!\! \mid \overline{C}\mid^2 \!\! \mathrm{d}x \mathrm{d}s + \\ &\frac{M_0 M_1^2}{2} \!\! \int_0^t \!\! g_{\lambda}(s) \mathrm{d}s. \end{split}$$

The application of the Gronwall's inequality yields $g_{\lambda}(t) \leqslant C\lambda$,

where C is a constant depending only on M_0, M_1, C_1, T and the measure of Ω , but independent on λ and t. Therefore.

$$\lim_{\lambda \to 0} g_{\lambda}(t) = 0, a.e. t \in (0,T),$$

which implies that

$$\overline{C} = C(u_1) - C(u_2) = 0$$
 a.e. in Q_T ,

$$C(u_1(x,t)) = C(u_2(x,t))a.e.(x,t) \in Q_T.$$

The proof is completed.

From the proof of the theorem 2.1, we have the

following result.

Theorem 2. 2 If both $\Phi_1(s)$ and $\Phi_2(s)$ are globally Lipschite continuous, and the set $E = \{s:$ A'(s) = 0 does not contain any interior point, then the initial boundary value problems $(1.1)\sim(1.3)$ has at most one generalized solution.

Proof Let $u_1, u_2 \in L^{\infty}(Q_T)$ be two generalized solutions of the problems $(1.1) \sim (1.3)$, from Theorems 2.1 and formula (2.1), we have

$$\begin{split} \iint_{Q_T} \overline{A} \Delta \varphi \, \mathrm{d}x \mathrm{d}t &= \iint_{Q_T} \vec{H} \cdot \bigtriangledown \varphi \, \mathrm{d}x \mathrm{d}t \leqslant \\ (\iint_{Q_T} |\vec{H}|^2 \mathrm{d}x \mathrm{d}t)^{1/2} (\iint_{Q_T} |\bigtriangledown \varphi|^2 \mathrm{d}x \mathrm{d}t)^{1/2} \leqslant \\ M_0 M_1 (\iint_{Q_T} |\overrightarrow{C}|^2 \mathrm{d}x \mathrm{d}t)^{1/2} (\iint_{Q_T} |\bigtriangledown \varphi|^2 \mathrm{d}x \mathrm{d}t)^{1/2} &= 0, \end{split}$$
 which implies that

$$\overline{A} = A(u_1) - A(u_2) = 0$$
 a. e. in Q_T for the arbitrariness of φ .

Since the set $E = \{s; A'(s) = 0\}$ does not contain any interior point, then A(s) is a strictly increasing function, hence we get

$$u_1(x,t) = u_2(x,t)$$
, a. e. $(x,t) \in Q_T$.

The proof is completed.

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(责任编辑: 蒋汉明 凌汉恩)