

# Zero-set Quasi-convex Functions and the Optimality Conditions of Zero-set Quasi-convex Programming

## 零集拟凸函数和零集拟凸规划的最优性条件

CHAO Mian-tao<sup>1</sup>, LIANG Dong-ying<sup>2</sup>  
晁绵涛<sup>1</sup>,梁东颖<sup>2</sup>

(1. Department of Mathematics and Computer Science, Guangxi College of Education, Nanning, Guangxi, 530023, China; 2. Guangxi Vocational and Technical College of Communications, Nanning, Guangxi, 530004, China)

(1.广西教育学院数学与计算机科学系,广西南宁 530023; 2.广西交通职业技术学院,广西南宁 530023)

**Abstract** A new class of generalized convex functions, which are called zero-set quasi-convex functions are defined, and some of their basic properties are discussed. According to the properties of the functions, sufficient optimality conditions for the nonlinear zero-set quasi-convex programming with inequality constraints are given.

**Key words** convex function zero-set quasi-convex function, zero-set quasi-convex programming, optimality conditions

摘要: 定义一种广义凸函数: 零集拟凸函数, 讨论其相关性质, 并结合函数性质给出零集拟凸不等式约束规划的最优性条件.

关键词: 凸函数 零集拟凸函数 零集拟凸规划 最优性条件

中图分类号: O 224 文献标识码: A 文章编号: 1005-9164(2008)03-0263-03

Convexity plays a vital role in many aspects of mathematical programming, for example, sufficient optimality conditions and duality theorems. Over the years, many generalized convexities were presented<sup>[1-4]</sup>. In this paper, we introduce a new class of functions, which are called zero-set quasi-convex functions and present some results of them. The results of optimality in zero-set quasi-convex programming problems with inequality constraints are established.

In the following, we review several concepts of generalized convexity which have some relationships with zero-set quasi-convexity. In this paper, we assume that the set  $S \subseteq \mathbb{R}^n$  is a nonempty convex set.

## 1 Definitions

**Definition 1. 1**<sup>[2]</sup> A real function  $f: S \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  is said to be quasi-convex function, if

$$f(\lambda x + (1 - \lambda)y) \leq \max\{f(x), f(y)\}, \forall x, y \in S, \forall \lambda \in (0, 1).$$

**Definition 1. 2**<sup>[2]</sup> Let  $f: S \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  be a differentiable function.  $f$  is said to be pseudo-convex function, if  $\forall x, y \in S$  with  $\nabla f(x)^T(y - x) \geq 0$  one can get  $f(y) \geq f(x)$ .

## 2 Zero-Set quasi-convex functions and their properties

In this section, we present the definition of zero-set quasi-convex function and discuss its main properties.

**Definition 2. 1** A function  $f: S \rightarrow \mathbb{R}$  is said to be zero-set quasi-convex on  $Z$ , if

$$f(\lambda x + (1 - \lambda)y) \leq \max\{f(x), f(y)\}, \forall x \in$$

收稿日期: 2008-01-17

作者简介: 晁绵涛 (1981-), 男, 硕士, 主要从事最优化理论与方法研究工作.

广西科学 2008年8月 第15卷第3期

$Z, \forall y \in S, \forall \lambda \in [0, 1]$ ,

where  $Z \subseteq \{x \in S \mid f(x) = 0\}$ .

**Proposition 2.1** If  $f(x)$  is a quasi- $\tau$ -convex function and  $Z = \{x \mid f(x) = 0\} \neq \emptyset$ , then  $f(x)$  is a zero-set quasi- $\epsilon$ -convex function on  $Z$ .

**Remark 2.1** The converse of Proposition 2.1 is not necessarily true. A counterexample is given as follows.

**Example 2.1** Let  $f: \mathbb{R} \rightarrow \mathbb{R}$  be defined as

$$f(x) = \begin{cases} (x+1)^2 - 2, & x \leq 0, \\ (x-1)^2 - 2, & x > 0. \end{cases}$$

The graph of the function  $f$  is shown in Fig. 1

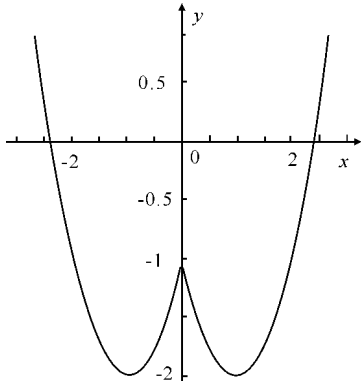


Fig. 1 Function  $f$

Let  $x_1 = -1, x_2 = 1, \lambda_0 = \frac{1}{2}$ , then

$$f(\lambda_0 x_1 + (1 - \lambda_0)x_2) = f(0) = -1 > \max\{f(x_1), f(x_2)\} = -2$$

So,  $f$  is not a quasi-convex function. On the other hand, from Fig. 1, one can see that  $f$  is a zero-set quasi-convex function (one can also get from Theorem 2.2).

**Proposition 2.2** Let  $f_i: S \rightarrow \mathbb{R} (i = 1, 2, \dots, m)$  be zero-set quasi-convex on  $Z_i = \{x \mid f_i(x) = 0\} (i = 1, 2, \dots, m)$  and  $Z = \bigcap_{i=1}^m Z_i \neq \emptyset$ , then  $f(x) = \max\{f_i(x), i = 1, 2, \dots, m\}$  is a zero-set quasi- $\tau$ -convex on  $Z$  i. e.,

$$f(\lambda x + (1 - \lambda)y) \leq \max\{f(x), f(y)\}, \forall x \in Z, \forall y \in S, \lambda \in [0, 1],$$

where  $S = \bigcap_{i=1}^m S_i$ .

**Proof** For  $\forall x \in Z, \forall y \in S$  and  $\forall \lambda \in [0, 1]$ , from the zero-set quasi-convexity of  $f_i(x)$ , we have

$$f(\lambda x + (1 - \lambda)y) = \max\{f_i(\lambda x + (1 - \lambda)y), i = 1, 2, \dots, m\} \leq \max\{\max\{f_i(x), f_i(y)\}, i = 1, 2, \dots, m\} = \max\{\max\{f_i(x), i = 1, 2, \dots, m\}, \max\{f_i(y), i = 1, 2, \dots, m\}\} = \max\{f(x), f(y)\}.$$

So,  $f(x)$  is zero-set quasi-convex on  $Z$ .

**Theorem 2.1** If continue function  $f(x)$  is a zero-set quasi-convex function on  $Z = \{x \mid f(x) = 0\}$ , then  $S_0 = \{x \mid f(x) \leq 0\}$  is a convex set.

**Proof** Suppose  $S_0$  is not a convex set, then there exist  $x, y \in S_0, \lambda \in (0, 1)$ , such that  $f(\lambda x + (1 - \lambda)y) > 0$ . If  $f(x) = 0$  or  $f(y) = 0$ , then from the zero-set quasi-convexity of  $f(x)$  we have  $f(\lambda x + (1 - \lambda)y) \leq \max\{f(x), f(y)\} \leq 0$ . So  $f(x), f(y) < 0$ . By the continue property of  $f(x)$ , one knows that there exist  $\bar{\lambda} \in (0, \lambda), \bar{\epsilon} \in (\lambda, 1)$ , such that

$$f(\bar{\lambda}x + (1 - \bar{\lambda})y) = 0, f(\bar{\epsilon}x + (1 - \bar{\epsilon})y) = 0.$$

Let  $\tilde{x} = \bar{\lambda}x + (1 - \bar{\lambda})y, \tilde{y} = \bar{\epsilon}x + (1 - \bar{\epsilon})y$ , one can easily know that there exist  $\lambda_0 \in (0, 1)$  such that  $\lambda_0 \tilde{x} + (1 - \lambda_0)\tilde{y} = \lambda x + (1 - \lambda)y$ .

On the other hand,

$$f(\lambda x + (1 - \lambda)y) = f(\lambda_0 \tilde{x} + (1 - \lambda_0)\tilde{y}) \leq \max\{f(\tilde{x}), f(\tilde{y})\}.$$

This is a contradiction. So,  $S_0 = \{x \mid f(x) \leq 0\}$  is a convex set.

**Theorem 2.2** Let  $f: S \rightarrow \mathbb{R}$ . If  $S_T = \{x \mid f(x) \leq T, x \in S\}$  is a convex set for each  $T \geq 0$  and  $Z = \{x \mid f(x) = 0\} \neq \emptyset$ , then  $f(x)$  is a zero-set quasi-convex function on  $Z$ .

**Proof** For  $\forall x \in Z, \forall y \in S$ . Let  $T_0 = \max\{f(x), f(y)\} \geq 0$ , then  $x, y \in S_{T_0}$ . So, from the convexity of  $S_{T_0}$ , we have  $\lambda x + (1 - \lambda)y \in S_{T_0}, \forall \lambda \in [0, 1]$ , i. e.,  $f(\lambda x + (1 - \lambda)y) \leq T_0 = \max\{f(x), f(y)\}, \forall \lambda \in [0, 1]$ . The proof of this theorem is completed.

**Theorem 2.3** Let  $f: S \rightarrow \mathbb{R}$  is zero-set quasi-convex on  $Z = \{x \mid f(x) = 0\}$ . If  $f$  is differentiable, then for  $\forall x \in Z, \forall y \in S$ , we have

- (i) if  $f(y) \leq 0$ , then  $\nabla f(x)^T (y - x) \leq 0$ ;
- (ii) if  $f(y) \geq 0$ , then  $\nabla f(y)^T (x - y) \leq 0$ ;
- (iii) if  $\nabla f(x)^T (y - x) > 0$ , then  $f(y) > 0$ ;
- (iv) if  $\nabla f(y)^T (x - y) < 0$ , then  $f(y) < 0$ .

**Proof** It is obviously that (i) and (iii), (ii) and (iv) are equivalent. It is only need to show the statements (i) and (ii).

$$(i) \text{ Suppose } x \in Z, y \in S \text{ and } f(y) \leq 0, \text{ then, } \nabla f(x)^T (y - x) = f'(x; y - x) = \lim_{\lambda \rightarrow 0^+} \frac{f(x + \lambda(y - x)) - f(x)}{\lambda} \leq \lim_{\lambda \rightarrow 0^+} \frac{\max\{f(x), f(y)\} - f(x)}{\lambda} = 0.$$

The statement (i) holds.

(ii) The proof is similar with (i). The proof of this theorem is completed.

### 3 Optimality conditions

In this section, we apply the associated results to the nonlinear programming problem with inequality constraints as follows

$$\begin{aligned} \min \quad & f(x) \\ (P_g) \quad \text{s. t.} \quad & g_i(x) \leq 0, i \in I = \{1, 2, \dots, m\}, \\ & x \in \mathbb{R}^n. \end{aligned}$$

Denote the feasible set of (P<sub>g</sub>) by  $S_g = \{x \in \mathbb{R}^n \mid g_i(x) \leq 0, i \in I\}$ . For convenience of discussion, we always assume that  $f$  and  $g_i$  are all differentiable and  $S_g$  is a nonempty set in  $\mathbb{R}^n$ .

**Theorem 3.1** If  $g_i(x) (i \in I)$  are zero-set quasi-convex functions, then the feasible set  $S_g$  of problem (P<sub>g</sub>) is a convex set.

**Proof** Let  $S = \{x \mid g_i(x) \leq 0, i \in I\}$ , from Theorem 2.1, one knows that  $S (i \in I)$  are all convex sets. So,  $S_g = \bigcap_{i \in I} S$  is a convex set.

**Theorem 3.2** Assume that  $x^*$  is a KKT point of (P<sub>g</sub>), and the function  $f(x)$  is differentiable and pseudo-convex,  $g_i(x) (i \in I)$  are differentiable and zero-set quasi-convex, then  $x^*$  is an optimal solution of the problem (P<sub>g</sub>).

**Proof** For any  $x \in S_g$ , we have  $g_i(x) \leq 0 = g_i(x^*)$ ,  $i \in I(x^*) = \{i \in I \mid g_i(x^*) = 0\}$ . Therefore, from the zero-set quasi-convexity of  $g_i(x)$ ,  $x \in S_g$  and Theorem 2.3, one can obtain  $\nabla g_i(x^*)^T (x - x^*) \leq 0$

for  $i \in I(x^*)$ .

Since  $x^*$  is the KKT point of (P<sub>g</sub>), there exist multipliers  $u_i \geq 0$  such that

$$\nabla f(x^*) + \sum_{i \in I} u_i \nabla g_i(x^*) = 0, u_i g_i(x^*) = 0.$$

From the above equation, we have

$$\begin{aligned} \nabla f(x^*)^T (x - x^*) &= - \sum_{i \in I} u_i \nabla g_i(x^*)^T (x - x^*) \\ &= - \sum_{i \in I(x^*)} u_i \nabla g_i(x^*)^T (x - x^*) \geq 0. \end{aligned}$$

Hence from the pseudo-convexity of  $f(x)$ , one can conclude  $f(x) \geq f(x^*)$ . Therefore  $x^*$  is an optimal solution of the problem (P<sub>g</sub>).

### References

- [1] Bector C R, Suneja S K, Lalitha C S. Generalized  $B$ - $v$ ex functions and generalized  $B$ - $v$ ex programming [J]. Journal of Optimization Theory and Applications, 1993, 76(3): 561-576.
- [2] Bazaraa M S, Sherali H D and Shetty C M. Nonlinear programming theory and algorithms second edition [M]. the United States of America John Wiley and Sons, 1993.
- [3] Youness E A.  $E$ -convex sets,  $E$ -convex functions and  $E$ -convex programming [J]. Journal of Optimization Theory and Applications, 1999, 102(2): 439-450.
- [4] Jian J B. On  $(E, F)$  generalized convexity [J]. International Journal of Mathematical Sciences, 2003, 2(1): 121-132.

(责任编辑: 尹 闯)

(上接第 262 页 Continue from page 262)

- [6] 甘作新, 葛渭高. 多非线性区间 Lurie 系统的鲁棒绝对稳定性 [J]. 辽宁师范大学学报: 自然科学版, 2000, 23(1): 9-14.
- [7] 马克茂, 王清. 带有时滞的区间 Lurie 系统的鲁棒绝对稳定性分析 [J]. 哈尔滨工业大学学报, 2006, 38(2): 170-173.
- [8] 马克茂. 区间系统鲁棒绝对稳定性分析 [J]. 系统工程与电子技术, 2006, 28(2): 280-283.
- [9] 黎克麟, 曾意. 具有多滞后的区间非线性 Lurie 控制系统的鲁棒绝对稳定性 [J]. 四川师范大学学报, 2007, 30(1): 27-30.
- [10] 俞立. 鲁棒控制——线性矩阵不等式处理方法 [M]. 北京: 清华大学出版社, 2002 6-22.

(责任编辑: 尹 闯)